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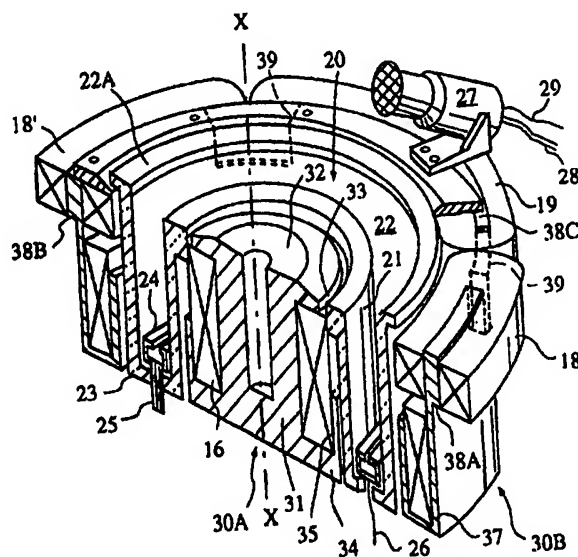
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(57) Abstract

In a Hall effect thruster (3A), especially for use in manoeuvring satellites (1A), a stream or plume of ions, used to produce the thrust, is deflected, by appropriate adjustment of a magnetic field, so as to steer the satellite or other vehicle. The channel (20), along which the ions are accelerated, is preferably flared outwardly at its open end so as to avoid erosion which would otherwise be caused by the deflection. The adjustment of the magnetic field is preferably achieved by dividing an outer magnetic pole, surrounding the channel (20), into separate sectors and winding individual electric coils (18, 19) around the sectors. Control of the current through these individual coils (18, 19) is used to make the appropriate adjustments of the magnetic field.

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A HALL EFFECT PLASMA THRUSTER

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Field of Invention

This invention relates to a Hall effect plasma thruster, also known as a closed electron drift thruster. The invention arose when considering the design of such thrusters for use on satellites or other spacecraft to assist in adjusting their positions when in orbit around the earth, to move them into the desired orbit or for propelling spacecraft during long missions.

Background of Invention

A conventional Hall effect thruster comprises an annular accelerating channel extending circumferentially around an axis of the thruster and also extending in an axial direction from a closed end to an open end. An anode is located, usually at the closed end of the channel, and a cathode is positioned outside the channel close to its open end. Means is provided for introducing a propellant, for example xenon gas, into the channel and this is often done through passages formed in the anode itself or close to the anode. A magnetic system applies a magnetic field in the radial direction across the channel and this causes electrons emitted from the cathode to move circumferentially around the channel. Some but not all of the electrons emitted from the cathode pass into the channel and are attracted towards the anode. The radial magnetic field deflects the electrons in a circumferential direction so that they move in a spiral trajectory, accumulating energy as they gradually drift towards the anode. In a

region close to the anode the electrons collide with atoms of the propellant, causing ionization. The resulting positively charged ions are accelerated by the electric field towards the open end of the channel, from which they are expelled at great velocity, thereby producing the desired thrust. Because the ions have a much greater mass than the electrons, they are not so readily influenced by the magnetic field and their direction of acceleration is therefore primarily axial rather than circumferential with respect to the channel. As realized by those electrons from the cathode that do not pass into the channel.

In this specification the terms "upstream" and "downstream" will be used for convenience to describe directions with reference to the movement of ions in the channel.

The Hall effect thruster has been widely developed and used, and has been the subject of a great number of publications. The operating principles and characteristics of such devices have been well known since the 1970's. In recent years, no fundamental changes to the operating principles of these devices have been made although there have been various proposals for improvement of particular details of design. One difficulty in the design of these thrusters arises from the erosion of insulator material at the outlet port of the thruster. If inaccuracies of manufacture lead to any misalignment between the geometric axis of the thruster and the thrust axis, this will cause non-symmetrical erosion of the insulator and lead to a decrease in efficiency and lifetime. One possible way of dealing with this problem is to set the electrical circuitry after manufacture so as to adjust the electrical currents passing through respective magnetic coils, thereby correcting any misalignment that would otherwise exist between the thrust axis and the geometric axis.

When in use, known thrusters of this type have always developed a thrust in a fixed direction. Hitherto this has been accepted without question; steering of the spacecraft being achieved either by the use of two thrusters and changing their relative amplitude of thrust; or by the use of a mechanism which swivels a

single thruster relative to the spacecraft. The use of two thrusters is expensive and increases weight and the swivelling mechanism is heavy, complex and expensive. It is believed that the present invention will make it possible to eliminate the need either for duplication of thrusters or for the use of a complex swivel mechanism.

The inv be suitably designed to cope with a misaligned axis of thrust, such "misalignment" can be created deliberately in a dynamically changeable basis so as to steer the satellite or other space vehicle in response to a signal indicating a desired change in the direction of thrust.

10 Summary of Invention

According to the invention there is provided a Hall effect thruster comprising a channel extending around an axis of the thruster and extending in an axial direction from a closed end to an open end, means for introducing a propellant into the channel and means for applying an axial electric field and a radial magnetic field so as to cause ionization of the propellant and acceleration of the resulting ions from the open end of the channel, characterized by steering means for varying the magnetic field in response to a steering signal thereby changing the direction in which the ions are accelerated and therefore the direction of thrust.

20 It is believed that by employing this technique it will be possible to steer the direction of the thrust through up to 5 degrees from the geometric axis independently in two orthogonal directions. This 5 degree deflection is believed to be sufficient for most purposes. Erosion of the insulator defining the channel along which ions are accelerated can be reduced to an acceptable level by designing this insulator so as to be flared outwardly at its open, downstream, 25 end. In arrangements where the downstream end of the channel is flared, it is preferred that the flare be created by an outward slope of the outer wall of the

channel. A similar inward slope of the inner wall would be possible. Alternatively, the design may be such that the inner wall extends downstream less far than the outer wall for the purposes of erosion limitation.

5 The propellant, which is typically xenon gas, is preferably introduced through or in the region of an anode and this anode preferably extends substantially all of the way around, as is conventional, between the anode at the closed end of the channel and one or more cathodes located outside the channel close to its open end. The or each cathode may either be located at a position which is radially outwardly of the channel or radially inwardly of the
10 channel.

The magnetic field is preferably generated by a central source of electromotive force (e.g. a coil or a permanent magnet) around which a number of additional sources of electromotive force (which may also be coils or electromagnets) are positioned. Where magnetic coils are used, the required
15 variation of the magnetic field can be achieved by independently varying the current through different coils.

The channel will normally be defined by a ceramic component because of the high temperatures which are generated. It preferably has a circular cross-section in a plane perpendicular to the axis of the thruster, although other,
20 non-circular configurations are possible. For example, where there are a number of coils or permanent magnets arranged around the outside of the channel, there can be an advantage in making the channel wider in regions adjacent those coils or permanent magnets.

In a preferred form of the invention the means for creating the magnetic
25 field comprises inner and outer magnetic bodies defining opposite magnetic poles and located respectively to the inside and outside of the channel. These magnetic bodies may be permanent magnets or electromagnets. Where the outer magnetic body is an electromagnet, it preferably has an associated electrical coil extending circumferentially around the axis of the thruster. This coil is preferably located

radially to the inside of the magnetic body between the magnetic body and an associated screening component which serves to reduce the magnetic field in the area of the anode. The outer magnetic body may be formed with gaps located circumferentially around it so that the magnetic pole which it defines of the magnetic body between the gaps. Each of these sub-poles has an associated electrical coil extending around it and passing through the gaps. The steering means varies the respective electric currents through the different coils so as to deflect the direction of thrust during operation of the thruster.

Brief Description of Drawings

One way of performing the invention will now be described with reference to the accompanying drawings in which:

Figure 1 illustrates, in schematic form, a known technique for steering satellites;

Figure 2 is an illustration similar to Figure 1, but showing schematically a satellite arranged to be steered using a technique in accordance with the invention;

Figure 3 is a perspective view of a stationary Hall effect plasma thruster constructed in accordance with the invention and illustrated as if cut through its diameter to reveal features of internal construction;

Figure 4 is a cross-section through the axis X-X of Figure 3 showing the magnetic components only and lines of magnetic force;

Figure 5 is a plan view of the components shown in Figure 4 but showing a design variation in which the magnetic poles are divided into four separate parts; and

Figure 6 is a schematic view of an alternate embodiment of the invention in which the gap between the walls of the thruster is larger near the magnetic poles than elsewhere.

Best Mode for Carrying Out Invention

Referring firstly to Figure 1, this shows, in very schematic form, a known arrangement in which a satellite 1, containing a power supply 2, is propelled by means of a plasma thruster 3. The thruster 3 contains an inner magnetic coil 4 and four outer magnetic coils 5, 6, 7 and 8 connected in series with the power supply 2 so as to receive equal constant currents. The thruster 3 can be adjusted mechanically by a swivel mechanism 9 under the control of a direction control circuit 10. The swivel mechanism comprises a platform 11 hinged at 12 to the satellite and at 13 to a driven shaft 14 of an actuator 15.

10 An arrangement constructed in accordance with the invention is shown in Figure 2, also very schematically, and comprises a satellite 1A having a thruster 3A connected rigidly to it; i.e. without the interposition of a swivel mechanism. The thruster 3A has an inner coil 16, an outer coil 17 and four ancillary steering coils 18, 18/, 19, 19/. A satellite power supply 2A is connected to a control circuit 10A which receives a direction signal SIG (e.g. from an earth station via
15 a radio link) defining a desired direction of thrust. The circuit 10A has twelve output lines arranged in pairs a1, a2; b1, b2; c1, c2; d1, d2; e1, e2; and f1, f2 and can apply a selected voltage of either polarity at each pair of outputs. The voltage a applied across a1 and a2 is constant, as is the voltage b applied across b1 and b2. The voltage c across c1 and c2 is of approximately the same value
20 as the voltage d across d1 and d2 though there may be a small offset between these values to correct for any misalignment that might otherwise exist between the axis of the thrust vector and the physical axis of the thruster; or to deliberately create such misalignment. The voltages c and d may be of the same or opposite signs depending on the connections to the corresponding coils 18, 18/
25 and are selected by the circuit 10A so as to ensure that current flows in opposite directions through coils 18, 18/, thereby controlling the direction of thrust in one plane. Voltages e and f are varied in the same way as (but independently of) voltages c and d so as to control the currents through coils 19, 19/ and thus the

direction of thrust in an orthogonal plane. In this way the direction of thrust can be adjusted through a total angle of up to 10 degrees in each plane as indicated in broken lines.

Referring now to Figures 3 and 4, the thruster is generally symmetrical about an axis X-X. It comprises an annular accelerating channel 20 defined between inner and outer walls 21, 22 respectively of a closed, downstream end (the bottom as shown on Figure 3) to an open, upstream end where the outer wall 22 extends in the downstream direction slightly further than the inner wall 21. Both inner and outer walls 21 and 22 are of increased thickness at their respective downstream ends and the outer wall 22 is chamfered at 22A so as to provide a slightly flared open end of the channel.

At the upstream end of the channel there is located a circular anode 24 in the form of a hollow square section tube having a groove extending continuously around it. A pipe 25 delivers a propellant (which is xenon gas in this particular example but could alternatively be krypton or argon) into this hollow anode from which it is delivered to the channel 20 through the circular groove. Baffles (not shown) may be supplied inside the anode in order to improve distribution of the propellant gas around the channel. An electrical connection 26 supplies positive potential to the anode.

A cathode 27 is mounted on a magnetic north pole, to be described later, close to the downstream end of the channel 20. This cathode is supplied with xenon gas through a connection 28 and with a source of negative potential via electrical connector 29. The magnetic system includes two magnetically separate bodies or yokes, namely an inner yoke 30A and an outer yoke 30B, both made of magnetically permeable material.

The inner yoke 30 is in the shape of a spool and has a central cylindrical core part 31 having a central bore for the purposes of weight reduction. An inner coil 16 is wound around this cylindrical part so that current passes in a clockwise direction as viewed from the downstream end. At the downstream end

of the cylindrical part 31 is a radially outwardly extending end-piece in the form of a flange 32 which defines at its free edge a first, circular pole 33 (magnetic south) of the inner magnetic yoke. Another end-piece in the form of a radially outwardly extending fl1 supports a cylindrical wall 35 which partly encloses the inner coil 32 and defines a second (magnetic north) pole at its free edge 36, as
5 seen best on Figure 4.

The outer yoke 30B is formed by a cylindrical wall 37 coaxial with the axis X-X and having a circular rim 38 of increased thickness. This rim is divided by four slots or gaps 39 (Figure 3) serving to divide the rim 38 into four
10 equal sectors 38A, 38B, 38C and 38D. Each of these sectors has a subsidiary, steering, coil wound around it. These steering coils are the same coils as are shown at 18, 18/, 19, 19/ on Figure 2 and they are arranged so that current passes clockwise around one and anticlockwise around the opposite coil. A first, radially inwardly extending end-piece, in the form of a flange 40, is attached to
15 the four sectors of the rim 38. This flange 40 is circular and bridges the gaps between the rim sectors 38. It is shown partly broken away on Figure 3 so as to reveal the underlying parts. The circular, radially inner, edge of the flange 40 forms a first (magnetic north) pole of the body 30B and is positioned, as is best seen on Figure 4, slightly downstream of the magnetic south pole 33 of the body
20 30A. The upstream end of the cylindrical wall 37 extends into another inwardly extending circular flange 41 which in turn extends into a cylindrical wall 42 coaxial with the axis X-X. The walls 37, 41 and 42 define an enclosure which contains a main outer coil 17 (also shown on Figure 2) which is wound around the wall 42 and is connected so that current flows in the direction shown in
25 Figure 4 such as to create a magnetic south pole at the downstream edge 43 of the wall 42 and a magnetic north pole at the inner edge 44 of the flange 40.

Figure 4 shows the lines of magnetic field when current is passing through the inner coil 16 and the outer coil 17 but not through the steering coils 18, 18/, 19 and 19/. It will be seen from Figure 4 that the offset between the

poles 33 and 44 results in the magnetic field being tilted in an annular accelerating zone 45 where, in operation, the ions are accelerated. This tilt of the magnetic field causes the ions to be accelerated in a direction shown by the arrows V towards the axis X-X. The purpose of this is to limit the divergence of the resulting plume of ions from the thruster. A point worth noting is that the cylindrical walls 35 and 42 serve to screen the area 45/ where the anode is located from the effects of the magnetic field.

Operation of the illustrated thruster is as follows. Electrons are emitted from the cathode 27 and are divided into two streams. One stream of such electrons is attracted towards the anode 24 into the annular channel 20. The radial component of the magnetic field within the channel causes the electrons to travel in a circumferential direction, gradually drifting in an axial direction towards the anode. In the region 45/ of the anode, where there is only minimal magnetic field, the electrons, having acquired energy during their spiral movement down the channel, cause ionization of the propellant gas supplied along the pipe 25.

The resulting ions, which are positively charged, are accelerated in a downstream direction by an electric field produced by a potential difference of about 300 volts, between anode and cathode. Because of their relatively high mass, as compared with the mass of electrons, the propellant ions are not greatly influenced by the magnetic field. There is however some such influence and the inclined nature of the magnetic field in the accelerating region 45 between poles 33 and 44 causes the stream of ions, issuing from the downstream end of the thruster, to tend to converge in the through the coils 18, 18/, the effect of the magnetic field on the ions issuing from one side of the thruster is increased because the magnetic field strength there is increased, whilst the effect is decreased on the opposite side of the thruster. Thus a deflection in the direction of the vector is achieved as shown at V/ and V// on Figure 4. By controlling the

currents through coils 18, 18/ on the one hand and 19, 19/ on the other hand, the direction of thrust can be displaced in any direction.

It was mentioned earlier that the electrons emitted from the cathode 27 were divided into two streams and that one of these streams entered the accelerating channel. The other stream of electrons is effective to neutralize the ions as they are ejected from the thruster so as to avoid leaving a resultant negative charge on the thruster. Erosion of the downstream edge of the outer ceramic wall 22, caused by steering of the thrust vector, is reduced by the presence of the chamfer 22a, whilst reduction in erosion of the corresponding edge of the inner wall 21 is reduced by its displacement in the upstream direction relative to the corresponding chamfered edge of the outer wall 22.

An important feature of the illustrated embodiment of the invention is that the magnetic bodies 30a and 30b are magnetically separate, each constituting an individual electromagnet having its own north and south poles. Because of this, it is possible to obtain the required magnetic characteristics within the accelerating channel with a wide variety of different overall dimensions of the magnetic system, different from those dimensions shown in Figures 3 and 4. For example, it is predicted that it will now be possible to manufacture Hall effect thrusters which, for a given power, are shorter in the axial direction and wider in diameter (or vice versa). A thruster can therefore now be designed which makes better use of available space on a satellite or in the launching vehicle.

Iody 30A defining the inner magnetic south pole is divided by radial slots into four segments S1, S2, S3 and S4; and the circular flange 40 defining the outer magnetic north pole is similarly divided into four segments N1, N2, N3 and N4. The slots or gaps between the thus formed individual north poles is notably smaller than the much larger slots or gaps 39 which accommodate the steering coils 18, 18/, 19, 19/. The individual north poles thus overlap end portions of the coils where they pass through the gaps. This design variation shown in Figure 5 provides improved steering capability.

Figure 6 depicts schematically an alternative design to that of Figure 5 with the alteration being in the shape of the channel 20. The distance between the walls of the channel 20 is greater at D1 adjacent the ancillary steering coils 18, 18', 19, 19', and is lesser at D2 at positions removed from the ancillary steering coils 18, 18', 19, 19'. It will be noted that erosion is reduced in this design during steering. A combination of chamfering, as seen at 22A in Figure 3, and varying the gap between the walls of the channel 20, as shown in Figure 6, can be utilized.

It will be appreciated that the particular embodiment of the invention shown in the drawings has been described only by way of example and that the invention is in no way limited to particular features of this example. For example, the invention is also applicable to the so-called anode layer thruster. Where a construction similar to that illustrated is used, various variations of design would be possible. For example, the steering effect could be improved by dividing the flange 40 into four separate sectors corresponding with the sectors 38a, 38b, 38c and 38d, thereby forming four separate main magnetic north poles. Another variation would be for the coil 17 to be located on the outside, rather than the inside, of the cylindrical magnetic wall 37. Another possible variation would be to omit the coil 17 and Also, either or both of the coils 16 and 17 could of course be replaced by permanent magnets. Alternatively the magnetic bodies 30A and 30B could be formed as permanent magnets. Yet another possible variation would be to have just three steering coils, or any number greater than four.

While the invention has been described in connection with specific embodiments thereof, it will be understood that it is capable of further modification, and this application is intended to cover any variations, uses, or adaptations of the invention following, in general, the principles of the invention and including such departures from the present disclosure as come within known or customary practice in the art to which the invention pertains and as may be

applied to the essential features hereinbefore set forth, and as fall within the scope of the invention and the limits of the appended claims.

CLAIMS

That which is claimed is:

- 1 1. In a Hall effect thruster comprising a channel extending around an
2 axis (X-X) of the thruster and extending in an axial direction from a closed end
3 to an open end, means for introducing a propellant into the channel and means
4 for applying an axial electric field and a radial magnetic field so as to cause
5 ionization of the propellant and acceleration of the resulting ions from the open
6 end of the channel, the improvement comprising:
7 steering means for varying the magnetic field in response to a steering
8 signal (SIG) thereby changing the direction in which the ions are
9 accelerated and therefore the direction of thrust.
- 1 2. A thruster according to claim 1, characterized in that the channel
2 is flared outwardly at a downstream end of the channel to reduce erosion of its
3 outer surface.
- 1 3. A thruster according to claim 2, characterized in that the steering
2 means allows a modification of the magnetic field independently along two axes
3 located in a plane perpendicular to a geometric axis of the thruster.
- 1 4. A thruster according to claim 3, characterized in that the steering
2 means comprises two pairs of magnetic coils, one on each of two opposite sides
3 of the thruster, connected so that the electric current passes through the coils in
4 dependence on the steering signal SIG.

1 5. A thruster according to claim 4, further including:
2 two pairs of magnetic coils arranged to control the direction of thrust in
3 respective orthogonal directions.

1 6. A thruster according to claim 5, characterized in that the means
2 for steering the magnetic field comprises inner and outer magnetic bodies
3 defining opposite magnetic poles and located respectively to the inside and
4 outside of the channel, the outer magnetic body extending around the channel and
5 being formed with gaps so that the magnetic pole which it defines is divided into
6 individual sub-poles each extending around an arcuate portion of the magnetic
7 body and having an associated electrical coil, the steering means being effective
8 to vary the respective currents through the different coils.

1 7. A thruster according to claim 6, in which the outer magnetic body
2 includes a circular pole piece which bridges the said gaps.

1 8. A thruster according to claim 6, in which the outer magnetic body
2 includes separate pole pieces arranged in a circle and serving partially to bridge
3 the gaps but having spaces between them smaller in the circumferential direction
4 than the gaps.

1 9. A thruster according to claim 8, including a main coil extending
2 circumferentially with respect to the outer magnetic body.

1 10. A thruster according to claim 9, in which the gaps are slots
2 extending in an axial direction along part but not all of the axial length of the
3 outer magnetic body.

1 11. A thruster according to claim 1, characterized in that the steering
2 means allows a modification of the magnetic field independently along two axes
3 located in a plane perpendicular to a geometric axis of the thruster.

1 12. A thruster according to claim 11, characterized in that the steering
2 means comprises two pairs of magnetic coils, one on each of two opposite sides
3 of the thruster, connected so that the electric current passes through the coils in
4 dependence on the steering signal SIG.

1 13. A thruster according to claim 1, characterized in that the steering
2 means comprises two pairs of magnetic coils, one on each of two opposite sides
3 of the thruster, connected so that the electric current passes through the coils in
4 dependence on the steering signal SIG.

1 14. A thruster according to claim 4, characterized in that the means
2 for steering the magnetic field comprises inner and outer magnetic bodies
3 defining opposite magnetic poles and located respectively to the inside and
4 outside of the channel, the outer magnetic body extending around the channel and
5 being formed with gaps so that the magnetic pole which it defines is divided into
6 individual sub-poles each extending around an arcuate portion of the magnetic
7 body and having an associated electrical coil, the steering means being effective
8 to vary the respective currents through the different coils.

1 15. A thruster according to claim 14, in which the outer magnetic
2 body includes a circular pole piece which bridges the said gaps.

1 16. A thruster according to claim 15, in which the outer magnetic
2 body includes separate pole pieces arranged in a circle and serving partially to
3 bridge the gaps but having spaces between them smaller in the circumferential
4 direction than the gaps.

1 17. A thruster according to claim 16, in which the gaps are slots
2 extending in an axial direction along part but not all of the axial length of the
3 outer magnetic body.

1 18. A thruster according to claim 17, in which the gaps are slots
2 extending in an axial direction along part but not all of the axial length of the
3 outer magnetic body.

1 19. A thruster according to claim 15, including a main coil extending
2 circumferentially with respect to the outer magnetic body.

1 20. A thruster according to claim 16, including a main coil extending
2 circumferentially with respect to the outer magnetic body.

1 21. A thruster according to claim 14, including a main coil extending
2 circumferentially with respect to the outer magnetic body.

1 22. A thruster according to claim 21, in which the gaps are slots
2 extending in an axial direction along part but not all of the axial length of the
3 outer magnetic body.

1 23. A thruster according to claim 6, in which the gaps are slots
2 extending in an axial direction along part but not all of the axial length of the
3 outer magnetic body.

1 24. A thruster according to claim 23, including a main coil extending
2 circumferentially with respect to the outer magnetic body.

1 25. A thruster according to claim 6, in which the gaps are slots
2 extending in an axial direction along part but not all of the axial length of the
3 outer magnetic body.

1 26. A thruster according to claim 14, in which the gaps are slots
2 extending in an axial direction along part but not all of the axial length of the
3 outer magnetic body.

1 27. A thruster according to claim 7, including a main coil extending
2 circumferentially with respect to the outer magnetic body.

1 28. A thruster according to claim 8, in which the gaps are slots
2 extending in an axial direction along part but not all of the axial length of the
3 outer magnetic body.

1 29. A thruster according to claim 1, characterized in that the channel
2 forms a larger gap adjacent the steering means than elsewhere to reduce erosion
3 of its outer surface.

1 30. A thruster according to claim 29, characterized in that the steering
2 means allows a modification of the magnetic field independently along two axes
3 located in a plane perpendicular to a geometric axis of the thruster.

1 31. A thruster according to claim 30, characterized in that the steering
2 means comprises two pairs of magnetic coils, one on each of two opposite sides
3 of the thruster, connected so that the electric current passes through the coils in
4 dependence on the steering signal SIG.

1 32. A thruster according to claim 31, further including:
2 two pairs of magnetic coils arranged to control the direction of thrust in
3 respective orthogonal directions.

1 33. A thruster according to claim 32, characterized in that the means
2 for steering the magnetic field comprises inner and outer magnetic bodies
3 defining opposite magnetic poles and located respectively to the inside and
4 outside of the channel, the outer magnetic body extending around the channel and
5 being formed with gaps so that the magnetic pole which it defines is divided into
6 individual sub-poles each extending around an arcuate portion of the magnetic
7 body and having an associated electrical coil, the steering means being effective
8 to vary the respective currents through the different coils.

1 34. A thruster according to claim 33, in which the outer magnetic
2 body includes a circular pole piece which bridges the said gaps.

1 35. A thruster according to claim 34, in which the outer magnetic
2 body includes separate pole pieces arranged in a circle and serving partially to
3 bridge the gaps but having spaces between them smaller in the circumferential
4 direction than the gaps.

1 36. A thruster according to claim 35, including a main coil extending
2 circumferentially with respect to the outer magnetic body.

1 37. A thruster according to claim 36, in which the gaps are slots
2 extending in an axial direction along part but not all of the axial length of the
3 outer magnetic body.

1 38. A satellite or other spacecraft or space platform comprising a
2 thruster according to claim 1, means for producing a steering signal SIG
3 indicating a thrust vector required to be applied to the satellite, spacecraft or
4 platform, and means for applying the steering signal to the steering means.

1 39. A satellite, spacecraft or space platform according to claim 38,
2 comprising a main body and characterized in that the thruster is connected rigidly
3 to the main body.

1 40. A satellite or other spacecraft or space platform comprising a
2 thruster according to claim 2, means for producing a steering signal SIG
3 indicating a thrust vector required to be applied to the satellite, spacecraft or
4 platform, and means for applying the steering signal to the steering means.

1 41. A satellite, spacecraft or space platform according to claim 40,
2 comprising a main body and characterized in that the thruster is connected rigidly
3 to the main body.

1 42. A satellite or other spacecraft or space platform comprising a
2 thruster according to claim 29, means for producing a steering signal SIG
3 indicating a thrust vector required to be applied to the satellite, spacecraft or
4 platform, and means for applying the steering signal to the steering means.

- 1 43. A satellite, spacecraft or space platform according to claim 42,
2 comprising a main body and characterized in that the thruster is connected rigidly
3 to the main body.

FIG. 1

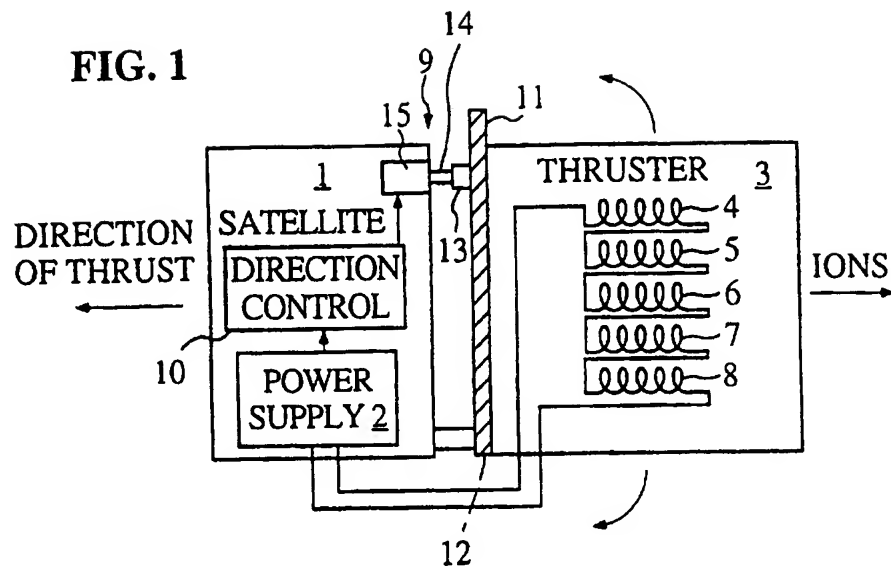
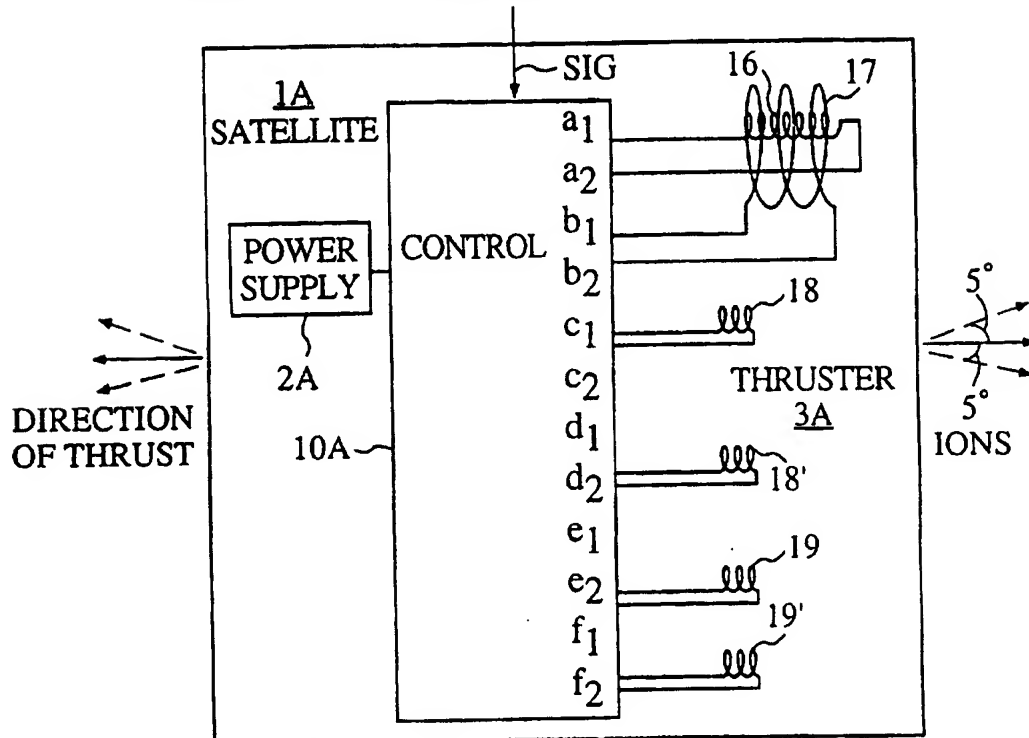


FIG. 2 DIRECTION DATA



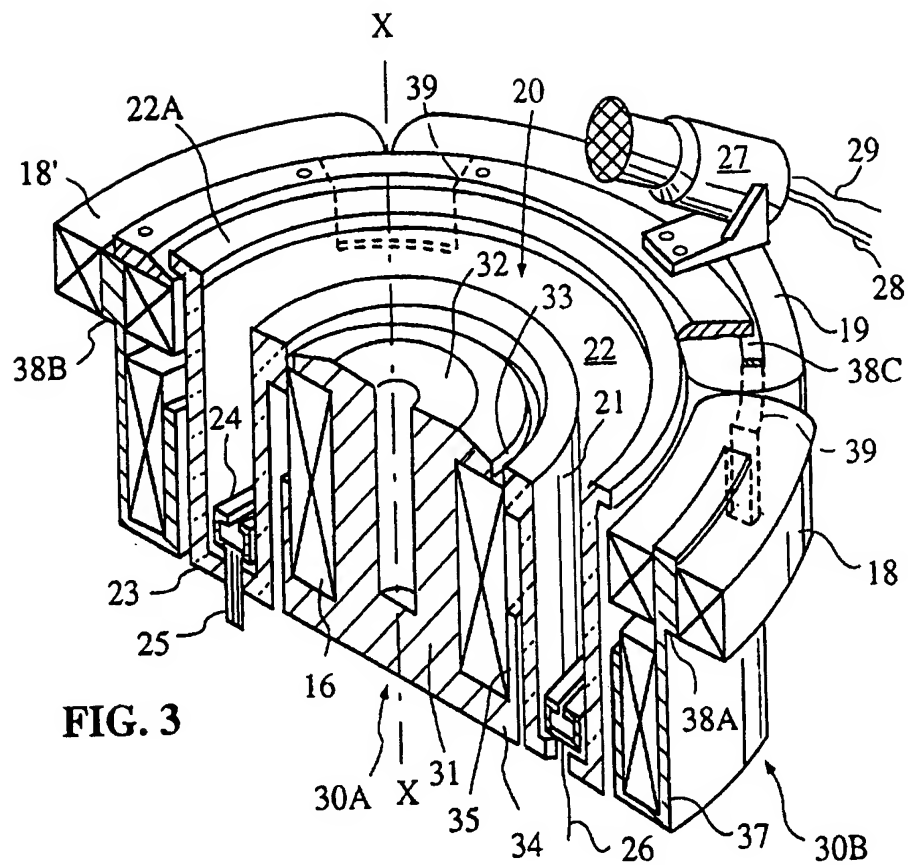


FIG. 3

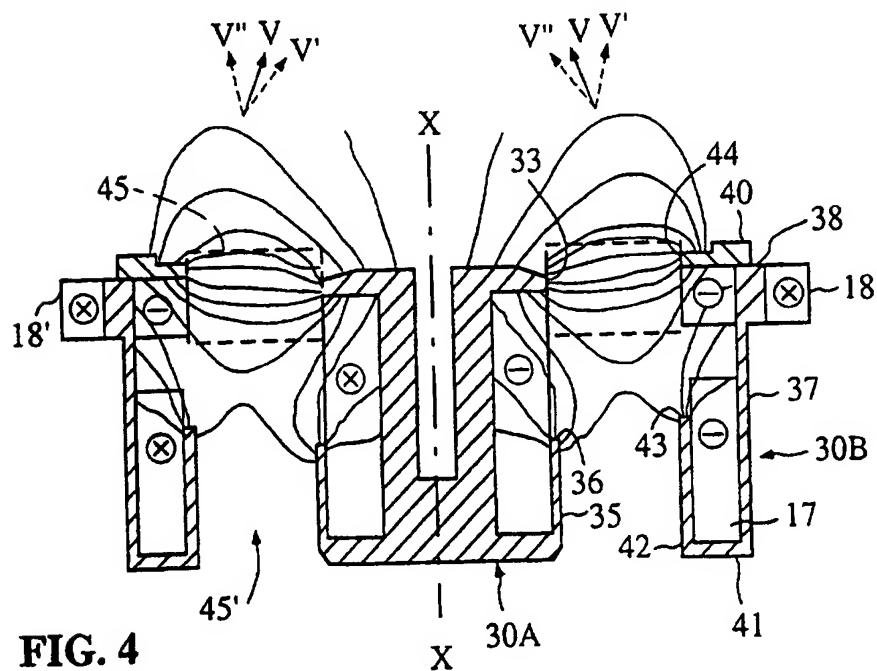


FIG. 4

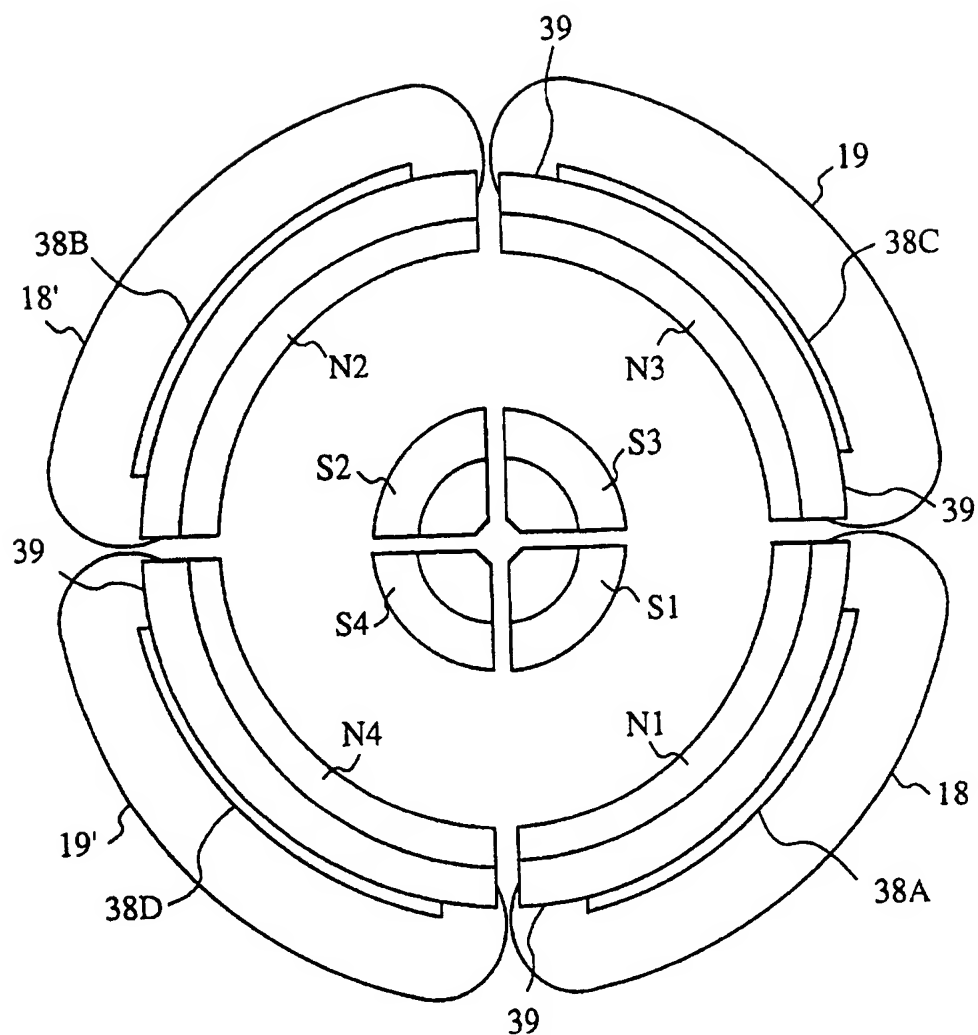


FIG. 5

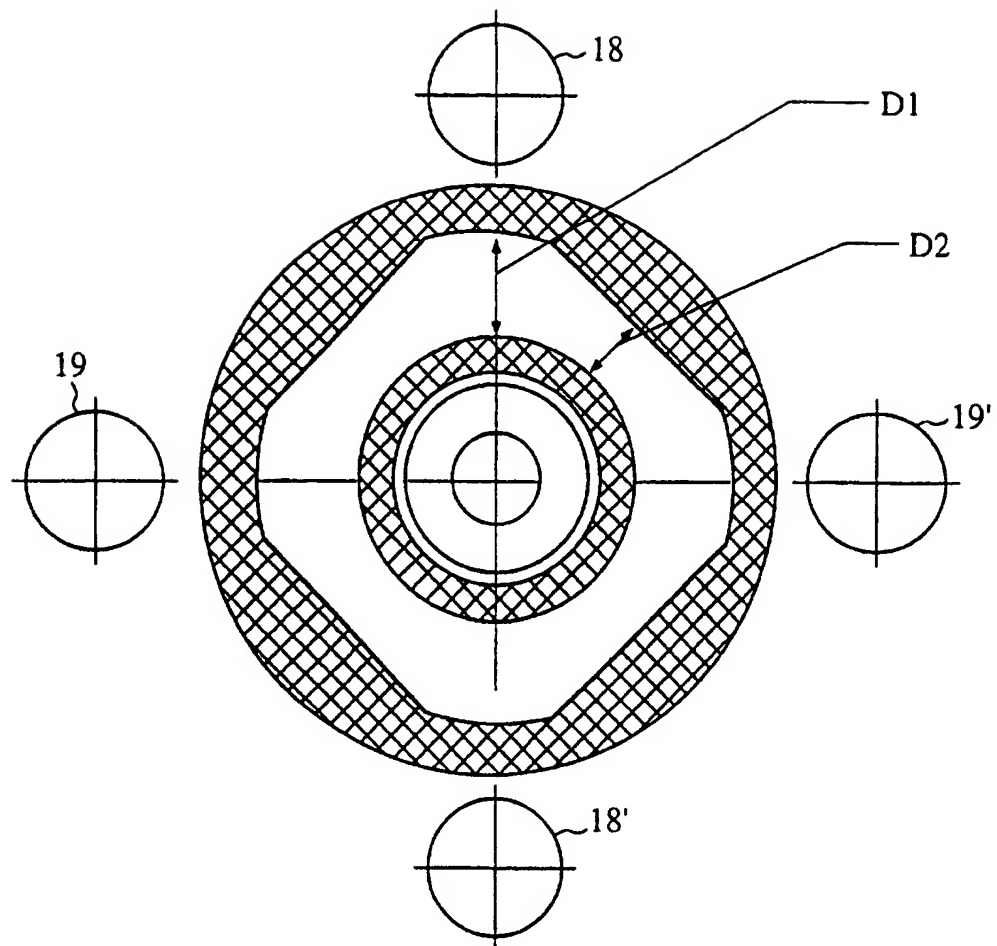


FIGURE 6

INTERNATIONAL SEARCH REPORT

International application No.
PCT/US97/05207

A. CLASSIFICATION OF SUBJECT MATTER

IPC(6) : F03H 1/00

US CL : 244/169

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

U.S. : 244/169, 204, 205; 60/202, 230

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
Y	US, A, 5,475,354 (VALENTIAN ET AL) 12 December 1995, see entire document	1-5, 11-13, 29-32, 38, 40-43
Y	US, A, 4,277,939 (HYMAN JR) 14 July 1981, see entire document	1-5, 11-13, 29-32, 38, 40-43
A	US, A, 3,735,591 (BURKHART) 29 May 1973, see entire document	
A	US, A, 4,862,032 (KAUFMAN ET AL) 29 August 1989, see entire document	
A	US, A, 3,225,236 (MEYER) 21 December 1965, see entire document	

☒ Further documents are listed in the continuation of Box C.
 ☐ See patent family annex.

* Special categories of cited documents:	*T* later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention
A document defining the general state of the art which is not considered to be of particular relevance	*X* document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone
E earlier document published on or after the international filing date	*Y* document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art
L document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)	*Z* document member of the same patent family
O document referring to an oral disclosure, use, exhibition or other means	
P document published prior to the international filing date but later than the priority date claimed	

Date of the actual completion of the international search 01 JULY 1997	Date of mailing of the international search report 13 AUG 1997
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INTERNATIONAL SEARCH REPORT

International application No.
PCT/US97/05207

C (Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	US, A, 3,106,058 (RICE) 08 October 1963, see entire document	